

IKUUKA





# Laser in Battery Production – how, where & why ?

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# KUKA

KUKA makes robots .... **But not only !**

2/3 =  
**Solution business**



- Arc & Laser Solutions
- Casting Solutions
- Advanced Welding Solutions
- Battery & PV assembly
- Customer Service und Technology Services

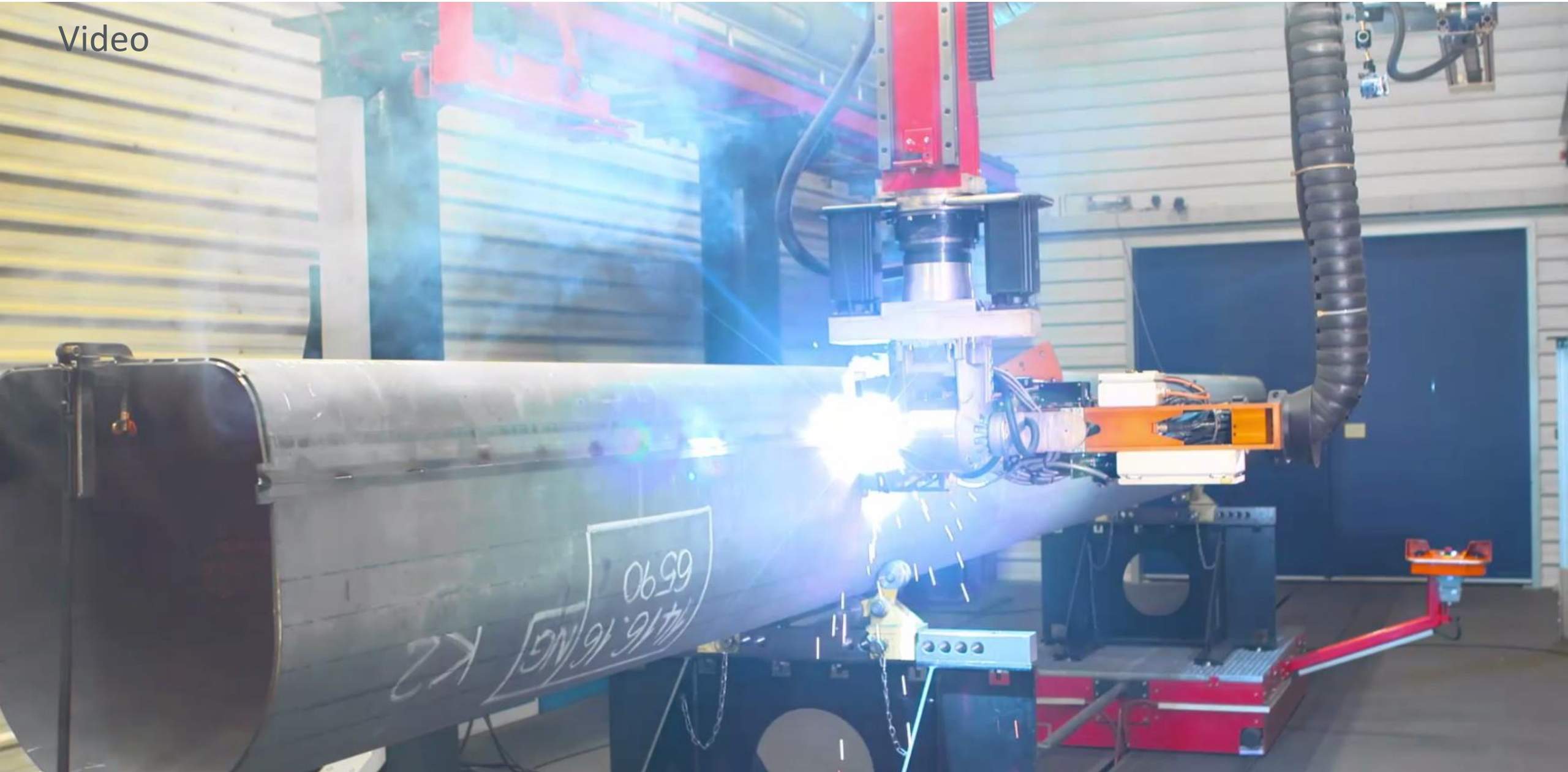


- Automotive Solutions
- Advanced Technology Solutions
- Aerospace Solutions
- Logistics Solutions
- Smart production | Industry 4.0

- Warehouse & Distribution Solutions
- Healthcare Solutions



Video





## EV-batteries – terminology & overview

### Packs

### Cells

cylindrical



prismatic



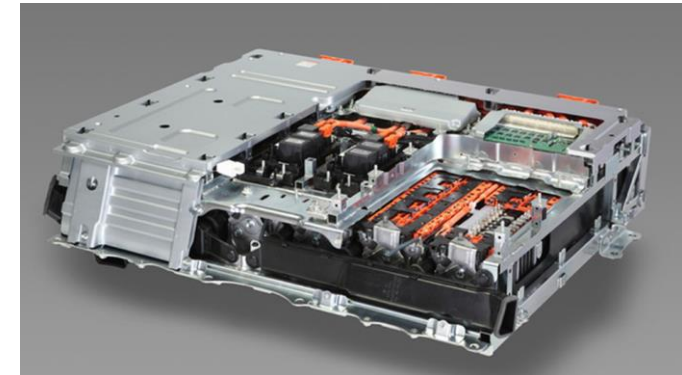
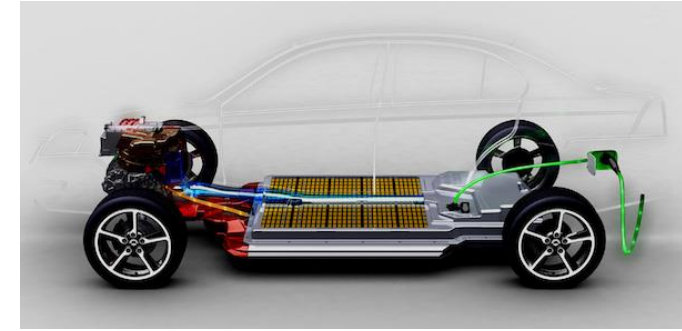
pouch

**3 basic types**

### Modules



**OEM-specific**



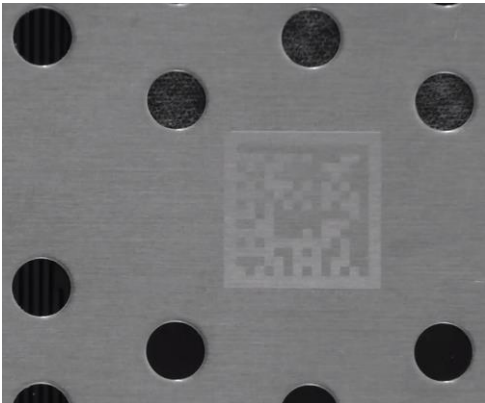
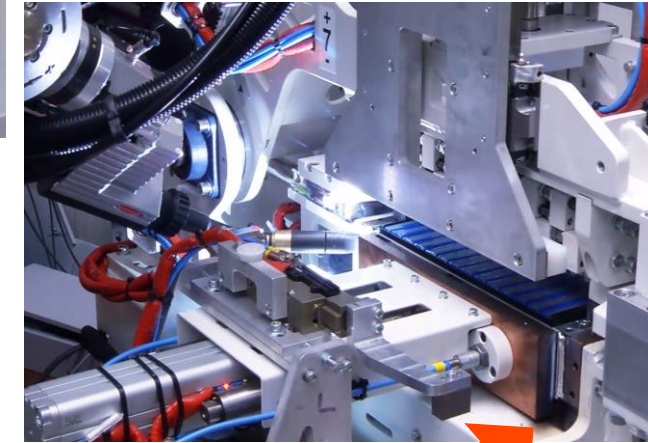
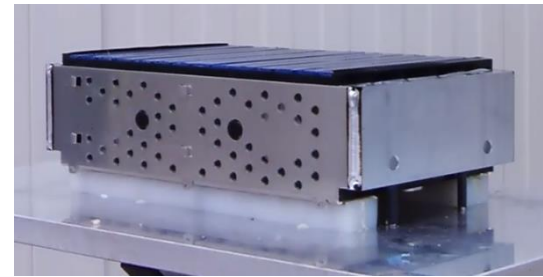
**Model-specific**



## Laser-applications in battery module assembly

- **Frame Welding:**

- Frame is solidly joined, to keep cells under pressure
- Arc welding or LASER welding (or screwing, riveting, ...)



- **Marking:**

- LASER scribing DMC (data matrix code) onto module frame

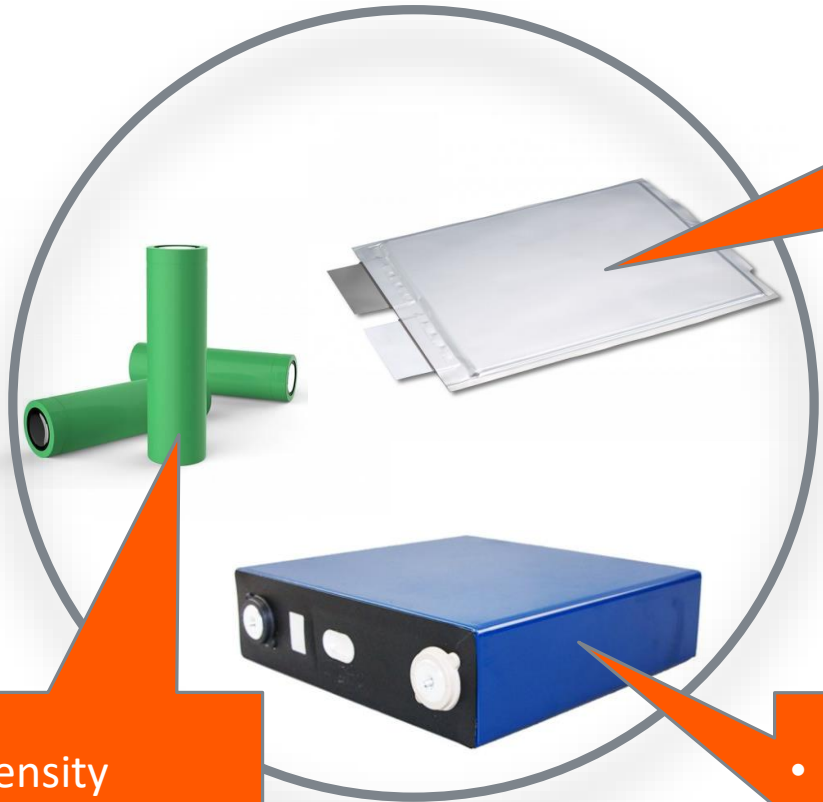
- **LASER surface processing:**

- Removal of Oxides from Al cell housing
- Surface preparation, e.g. before application of insulating tape or other coating



Source: <https://cdn1.img.sputniknews.com/images/104492/37/1044923772.jpg>

## Cell geometry: one origin, three concepts



- Flexibility
- Weight
- Flat electrodes

- Energy density
- Maturity
- Thermal properties

- Safety
- Form factor
- Capacity



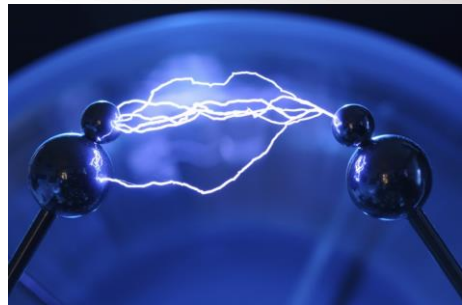
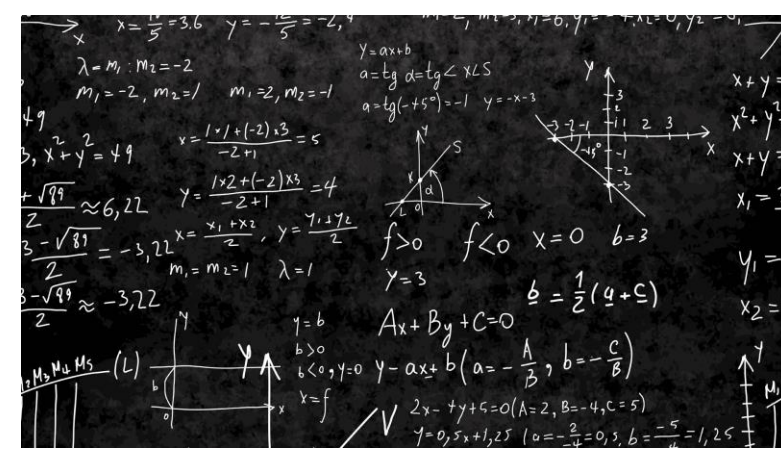
## Electrical contacting of cells in EV battery (I)

### Specific requirements

#### 1. Trend to HV-batteries for EVs (electrical vehicles): 400 - 800 V

– Li-Ion cell voltage: ca. 3.6 V → 1-200 cells in series (one bad joint impacts complete string!)

→ need for very robust, reliable process



#### 2. Trend to high power EVs: up to 750 kW (1000 PS)

– with 375V HV battery → currents up to 2.000 A

– depending on cell type & battery capacity: 5 – 150 strings → 15 – 400 A in one string

→ need for minimal contact resistance

#### 3. Trend to high capacity batteries: up to > 100 kWh

– depending on cell-type: several 100 to about 10.000 individual cells

– up to ca. 40.000 welding points per battery (e.g. wire/tab bonding)

→ need for fast & cost efficient contacting process





## Electrical contacting of cells in EV battery (II)

### Specific requirements

#### 4. Contacting of different materials

- for pouch cells, Cu and Al electrodes must be contacted
- different conductor materials must be joined
- need for process capable of intermetallic joints



#### 5. Heat impact reduces battery life

- process must minimize heat influx to cell



#### 6. Batteries are subject to mechanical stress:

- thermal cycles, vibrations, ...

- process must create mechanically solid bond



## Electrical contacting of cells in EV battery (III)

### Specific requirements

- investment cost (purchase cost, write-off period, overall system cost, ...)
- operational cost (maintenance, consumables, energy)

→ need for competitive, cost efficient process equipment

### 7. Cost



### 8. Safety

→ process equipment must be safe to use

### 9. Flexibility

- evolution of welding process details
- varying material combinations & joint topologies

→ process parameters must be easily adjustable



### 10. Availability

- minimized maintenance & repair needs
- maximized duty cycled

→ process equipment must ensure high, reliable availability







## Typical welding processes

- **Resistance welding (gap welding, projection welding)**
  - + : established, cheap technology;
  - : Accessibility; surface requirements; contact area; heat influx; limited material combinations;
- **Ultrasonic welding**
  - + : Small heat impact; lower surface requirements;
  - : Sensitive to surface quality; small contact area; limited material combinations; cycle times;
- **Friction Welding (liner, rotational, FSW)**
  - + : Material combinations possible; good contacting; not sensitive to surface properties;
  - : Forces; cycle times;
- **EMP Welding (electro-magnetic pulse welding)**
  - + : Larger contact areas;
  - : Forces, process control;
- **LASER**
  - + : Fast (using scanning technology, no need for physical position); flexible; material combinations;
  - : Cost; safety;
- **Other technologies (Clamping, screwing, gluing, ...)**
  - + : Avoiding heat impact; potentially fast; benefits for recycling;
  - : Joint quality / robustness;

## Tactile versus scanner based bonding

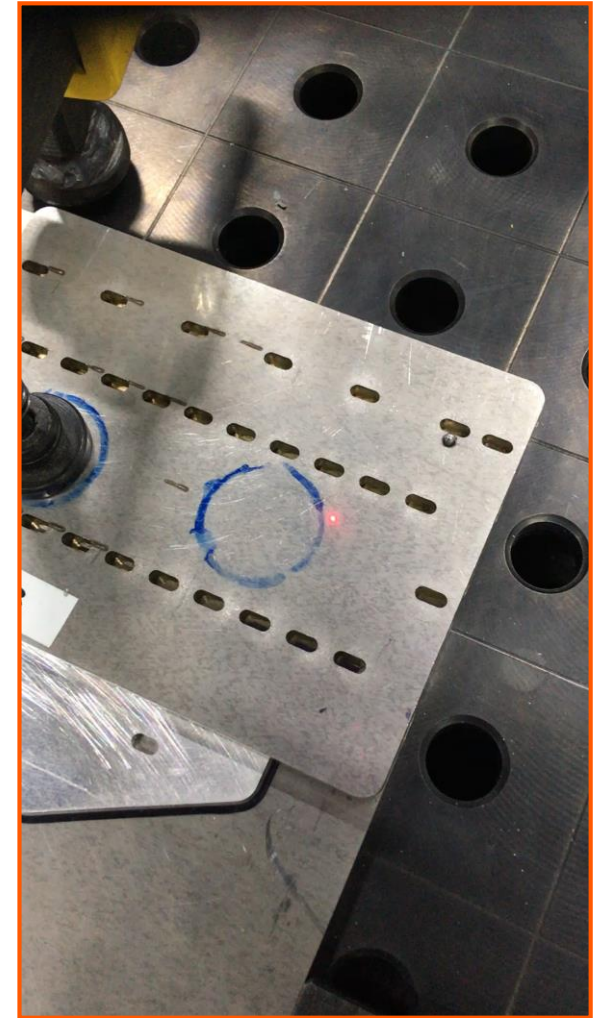


Tactile welding technologies  
(e.g. wire bonding, resistance / gap welding, etc.)

- + well established, robust, “cheap”
- slow, spacious, prone to wear

Scanner based welding technologies  
(e.g. laser, electron beam, ...)

- + very fast, scalable contact area, optional “on the fly” process, minimal maintenance
- demanding fixturing, more complex,





## Contacting cylindrical cells



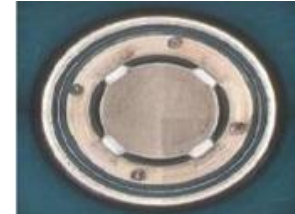
- cell size / capacity  
→ huge number of welds

- thermal contacting,  
assembly process  
→ negative contact on top  
rim

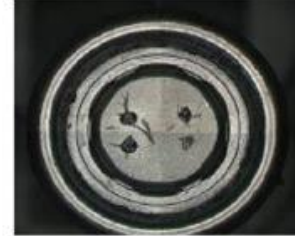
### The ideal candidate for laser welding ?

**Unfortunately .....**

MAXELL  
PB



SANYO



SDI  
13Q



SONY



EONE

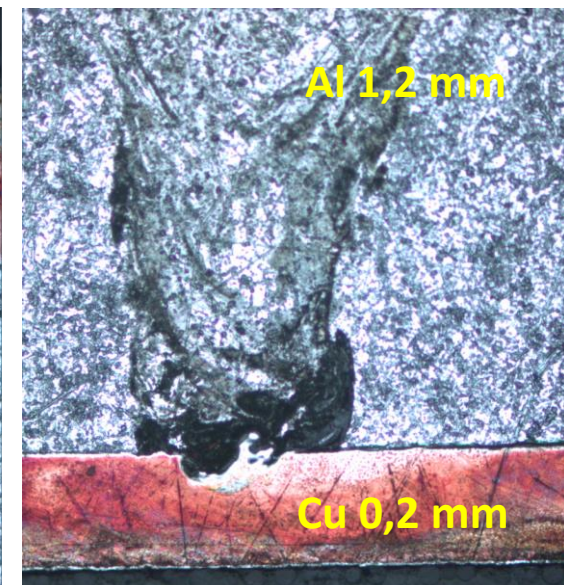
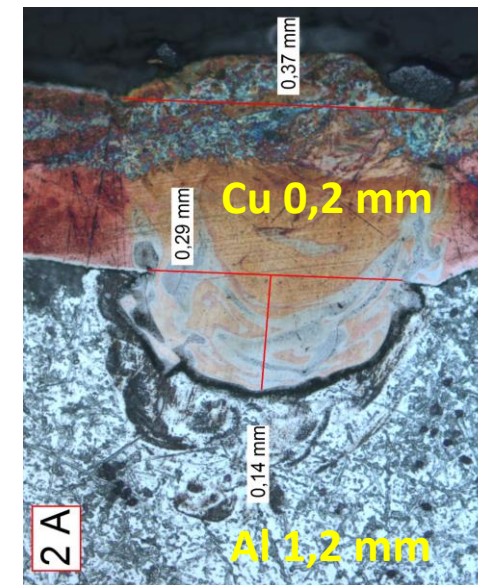
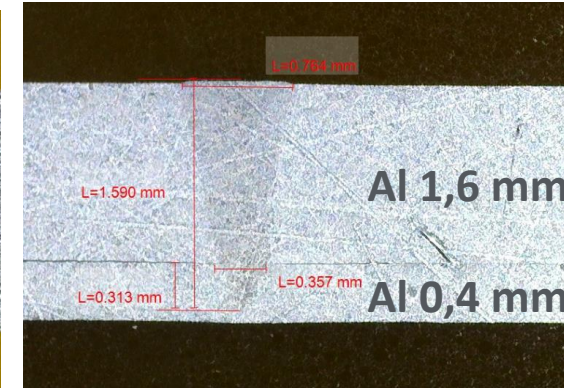
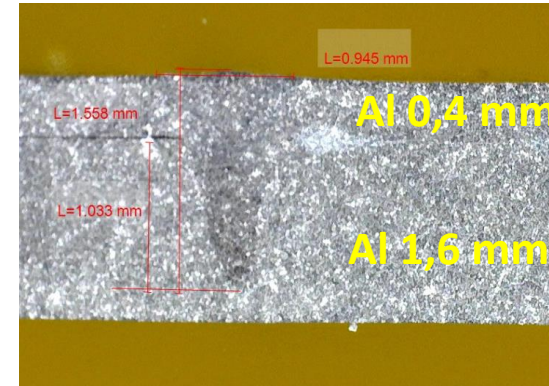


## Challenging special applications: electrode contacting for pouch cells



### Success factors:

- Laser equipment / selection
- Process expertise / implementation
- Fixtures / tooling
- Product design



### Specific challenge:

- Contacting of thin Al & Cu electrodes ....
- ... to each other
- ... and/or to thick current collectors
- ... with minimal space consumption
- ... and high reliability





## Conclusion

- Mass production challenges (“6 sigma”):
  - Tolerances (dimensions, positioning, thickness, surface properties, ...)
  - Technical availability (wear parts, process drifts, ...)
  - Robustness (maintenance & calibration needs)

require *team work*

**Process & Concept** (→ research / academia)  
**x Tool & Fixture Design** (→ machine builder / integrator)  
**x Product Design** (→ cell / battery producer)  
**= Result**

# Thank you ! Questions ?



## Intelligent automation for e-mobility





**KUKA**

**Thank you !  
Questions ?**

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